

# Lineární zobrazení

$$Q: U \rightarrow V$$

$$Q(\alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2 + \dots + \alpha_m \vec{v}_m) = \alpha_1 Q(\vec{v}_1) + \dots + \alpha_m Q(\vec{v}_m)$$

Pr. Prohodněte, zda  $Q: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  je L $\mathbb{R}$

$$Q(x_1, x_2, x_3) := (x_1 - 2x_2, 2x_1 + x_3, x_1 + x_2 + x_3)^T$$

$$\begin{array}{l} 1) Q(\vec{x} + \vec{y}) \stackrel{?}{=} Q(\vec{x}) + Q(\vec{y}) \\ 2) Q(\alpha \vec{x}) = \alpha Q(\vec{x}) \end{array}$$

$$= \begin{pmatrix} 1 & -2 & 0 \\ 2 & 0 & 1 \\ 1 & 1 & 1 \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

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Ano, je L $\mathbb{R}$ .

Pr. Dáno lin. zobr.  $Q: \mathbb{R}^3 \rightarrow \mathbb{R}^2$

$$Q\left(\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}\right) := \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \quad Q\left(\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}\right) := \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \quad Q\left(\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}\right) := \begin{pmatrix} 2 \\ -1 \end{pmatrix}.$$

Vypočítejte  $Q\left(\begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix}\right)$ .

1) Hledám  $\alpha_1, \alpha_2, \alpha_3 \in \mathbb{R}$ :  $\alpha_1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + \dots + \alpha_3 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix}$

$$\left( \begin{array}{ccc|c} 1 & 1 & 0 & 2 \\ 0 & 1 & 1 & -2 \\ 0 & 1 & 0 & 1 \end{array} \right) \xrightarrow{-r_2} \sim \left( \begin{array}{ccc|c} 1 & 1 & 0 & 2 \\ 0 & 0 & 1 & -4 \\ 0 & 1 & 0 & 1 \end{array} \right) \Rightarrow \alpha_3 = -4$$
$$\Rightarrow \underline{\alpha_2 = 1}$$

$$2) \underline{Q\left(\begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix}\right)} = \alpha_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + \alpha_2 \begin{pmatrix} -1 \\ 1 \end{pmatrix} + \alpha_3 \begin{pmatrix} 2 \\ -1 \end{pmatrix} \quad \begin{array}{l} \text{1. rov.: } \alpha_1 + 1 = 2 \\ \underline{\alpha_1 = 1} \end{array}$$

$$= 1 \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix} + 1 \cdot \begin{pmatrix} -1 \\ 1 \end{pmatrix} - 4 \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$
$$= \underline{\underline{\begin{pmatrix} -8 \\ 7 \end{pmatrix}}}$$

kvadr. funkce

Pr. Dáno lin. zobr.  $Q: \mathbb{P}_2 \rightarrow \mathbb{P}^2$

$$a(\underline{1+x}) := \begin{pmatrix} 1 \\ 1 \end{pmatrix}, a(\underline{1+x+x^2}) := \begin{pmatrix} 1 \\ 0 \end{pmatrix}, a(\underline{x}) := \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

Najděte alešpoň jeden  $p(x) \in \mathbb{P}_2: a(p) = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$

1) Hledám  $\alpha_1, \alpha_2, \alpha_3 \in \mathbb{R}: \alpha_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \alpha_2 \begin{pmatrix} -1 \\ 0 \end{pmatrix} + \alpha_3 \begin{pmatrix} 2 \\ -1 \end{pmatrix} = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$

$$\left( \begin{array}{ccc|c} 1 & -1 & 2 & 2 \\ 1 & 0 & -1 & 3 \end{array} \right) \xrightarrow{-r_1} \sim \left( \begin{array}{ccc|c} 1 & -1 & 2 & 2 \\ 0 & 1 & -3 & 1 \end{array} \right)$$

$$\begin{array}{l} \alpha_3 = t, t \in \mathbb{R} \\ \text{2. v.} \cdot \alpha_2 = 1 + 3t \\ \text{1. v.} \cdot \alpha_1 = 2 + (1 + 3t) - 2t \\ \alpha_1 = 3 + t \end{array} /$$

$$2) p(x) = (3+t) \cdot (1+x) + (1+3t) \cdot (1+x+x^2) + t \cdot x$$

nejs. pro  $t=0: \underline{p(x) = 3 \cdot (1+x) + (1+x+x^2) + 0 \cdot x = 4 + 4x + x^2}$

Př.  $\mathcal{A}: \mathbb{R}^3 \rightarrow \mathbb{R}^2$   $a\left(\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 1 \\ 2 \end{pmatrix}, a\left(\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} -1 \\ 1 \end{pmatrix}, a\left(\begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$

Napište  $\mathcal{R}(a), h(a), n(a), d(a)$

obor  $\mathcal{R}(a)$   $\mathcal{R}(a)$   $\mathcal{R}(a)$   $\mathcal{R}(a)$   
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obor  $\mathcal{R}(a)$   $\mathcal{R}(a)$   $\mathcal{R}(a)$   $\mathcal{R}(a)$   
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$$\mathcal{R}(a) = \left( \begin{array}{cc} 1 & 2 \\ -1 & 1 \\ 2 & -1 \end{array} \right) \xrightarrow{-2r_1} \sim \left( \begin{array}{cc} 1 & 2 \\ 0 & 3 \\ 0 & -5 \end{array} \right) \xrightarrow{+5/3 r_2}$$

$$\underline{\mathcal{R}(a)} = \left\langle \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ -1 \end{pmatrix} \right\rangle = \left\langle \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 3 \end{pmatrix} \right\rangle$$

$$\underline{h(a)} = \dim \mathcal{R}(a) = \underline{2}$$

2)  $n(a) = \dim \mathcal{N}(a) = 3 - 2 = 1$

$$N(a) = \left\{ x \in \mathbb{R}^3 : A(\bar{x}) = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right\}$$

$$\begin{pmatrix} x_1 & x_2 & x_3 \\ 1 & -1 & 2 \\ 2 & 1 & -1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix} \xrightarrow{-2 \rightarrow R_1} \sim \begin{pmatrix} 1 & -1 & 2 \\ 0 & 3 & -5 \end{pmatrix}$$

$$N(a) = \left\{ -\frac{1}{3}t \cdot \begin{pmatrix} 1 \\ 3 \\ 3 \end{pmatrix} + \frac{5}{3}t \cdot \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + t \cdot \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} : t \in \mathbb{R} \right\}$$

$\alpha_3 = t$   
 2. ř. :  $\alpha_2 = \frac{5}{3}t$   
 1. ř. :  $\alpha_1 = \alpha_2 - 2\alpha_3 = \frac{5}{3}t - 2t = -\frac{1}{3}t$

$$= \left\{ t \cdot \begin{pmatrix} -1/3 \\ 1 \\ 1 \end{pmatrix} : t \in \mathbb{R} \right\} = \left\langle \begin{pmatrix} -1/3 \\ 1 \\ 1 \end{pmatrix} \right\rangle$$

$$\underline{d(a)} = \dim N(a) = \underline{1}$$

$$\text{Zk.: } \underbrace{h(a)}_2 + \underbrace{d(a)}_1 = \dim \mathbb{R}^3 = 3$$

Př. Najděte matici lin. zob.  $A: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  vzhledem ke kanonickému (standardnímu) bázi,  $A(x_1, x_2, x_3) := (x_1 + x_2, x_2 - 2x_3)$

$$= \begin{pmatrix} 1x_1 + 1x_2 + 0x_3 \\ 0x_1 + 1x_2 - 2x_3 \end{pmatrix} = \underline{\underline{\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & -2 \end{pmatrix}}}$$