

Bilinearform

$$B: V \times V \rightarrow \mathbb{R}$$

- linear in 1. argument
- linear in 2. argument

Pr.

$$B(\bar{u}, \bar{v}) := \underbrace{u_1 v_1 + u_2 v_1 - 2u_2 v_2}_{\mathbb{B}} \quad \text{na } \mathbb{R}^2$$
$$= \underbrace{u_1}_{\mathbb{B}} (1v_1 + 0v_2) + u_2 (1v_1 - 2v_2)$$
$$= (u_1, u_2) \cdot \underbrace{\begin{pmatrix} 1 & 0 \\ 1 & -2 \end{pmatrix}}_{\mathbb{B}} \cdot \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \Rightarrow B \text{ je bilinear' forma}$$

Obecně

$B: V \times V \rightarrow \mathbb{R}$.. bilinear' forma

$E = (\bar{e}_1, \dots, \bar{e}_n)$.. báze V

$$\bar{u}, \bar{v} \in V \Rightarrow \exists! \alpha, \beta \in \mathbb{R}^n : \bar{u} = \alpha_1 \bar{e}_1 + \dots + \alpha_n \bar{e}_n$$
$$\bar{v} = \beta_1 \bar{e}_1 + \dots + \beta_n \bar{e}_n$$

$$B(\bar{u}, \bar{v}) = [\bar{u}]_E^T \cdot \mathbb{B}_E \cdot [\bar{v}]_E$$

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$$B(\alpha_1 \bar{e}_1 + \dots + \alpha_n \bar{e}_n, \beta_1 \bar{e}_1 + \dots + \beta_n \bar{e}_n)$$

lin. v 2. argumentu

$$\sum_{j=1}^n \beta_j \cdot B(\alpha_1 \bar{e}_1 + \dots + \alpha_n \bar{e}_n, \bar{e}_j)$$

$j=1$ // (každý s 1. argumentem)

$$\sum_{i=1}^n \alpha_i \sum_{j=1}^n B(\bar{e}_i, \bar{e}_j) \beta_j$$

$$\begin{aligned} & \parallel \\ & \bar{\alpha}^T \cdot \begin{bmatrix} B(\bar{e}_1, \bar{e}_1) & B(\bar{e}_1, \bar{e}_2) & \dots & B(\bar{e}_1, \bar{e}_n) \\ B(\bar{e}_2, \bar{e}_1) & B(\bar{e}_2, \bar{e}_2) & \dots & B(\bar{e}_2, \bar{e}_n) \\ \vdots & \vdots & \ddots & \vdots \\ B(\bar{e}_n, \bar{e}_1) & B(\bar{e}_n, \bar{e}_2) & \dots & B(\bar{e}_n, \bar{e}_n) \end{bmatrix} \parallel \\ & \underbrace{[\bar{u}]_E^T}_{\text{red}} \cdot \underbrace{\bar{B}}_{\text{red}} \end{aligned}$$

B_E .. matice bilineární formy vzhledem k bázi E

Změna matice B při změně báze

Změna souřadnic (při změně báze)

je lineární transformací $T_{E,F}(\bar{\alpha}) = \underbrace{T_{E,F}}_{\parallel [\bar{u}]_E} \cdot \underbrace{[\bar{u}]_E}_{\parallel [\bar{u}]_F}$

$$E = (\bar{e}_1, \dots, \bar{e}_n) \rightarrow F = (\bar{f}_1, \dots, \bar{f}_n)$$

$\bar{u} \in V$

$$\bar{u} = \alpha_1 \bar{e}_1 + \dots + \alpha_n \bar{e}_n \quad \bar{u} = \beta_1 \bar{f}_1 + \dots + \beta_n \bar{f}_n$$

$$T_{E,F} \cdot \bar{\alpha} = \bar{B}$$

$$\begin{aligned} \Rightarrow B(\bar{u}, \bar{v}) &= [\bar{u}]_E^T \cdot B_E \cdot [\bar{v}]_E \\ B(\bar{u}, \bar{v}) &= [\bar{u}]_F^T \cdot B_F \cdot [\bar{v}]_F \end{aligned}$$

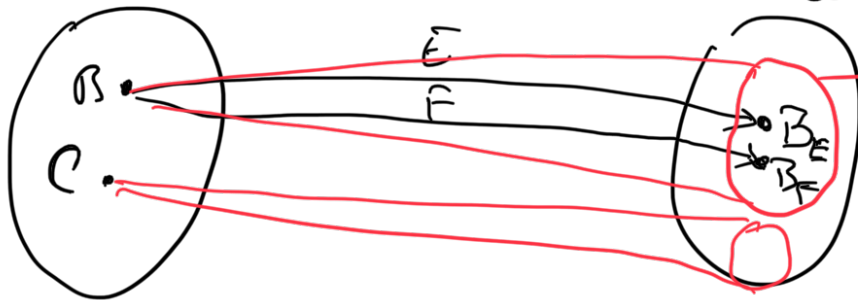
$${}^I (T \cdot [\bar{u}]_E)^T \cdot B_F \cdot T \cdot [v]_E$$

$${}^I [\bar{u}]_E^T \cdot T^T \cdot B_F \cdot T \cdot [v]_E$$

$\begin{matrix} B_E \\ \parallel \\ T^T B_F T \end{matrix}$

regulární matice
 kongruentní matice

Bilineární forma θ



Ekvivalentní matice má

stejná kongruentní matice

Symetrická matice (bilineární forma)

$${}^I \theta_{ij} : (B)_{ij} = (B)_{ji} \iff \boxed{B = B^T}$$

Pr. a) $\begin{pmatrix} 1 & 2 \\ 2 & -1 \end{pmatrix}$ je symetrická!

b) $\begin{pmatrix} 0 & -1 & 2 \\ -1 & 0 & 3 \\ 2 & 3 & 0 \end{pmatrix} : \begin{pmatrix} 0 & -1 & 2 \\ -1 & 0 & 3 \\ 2 & 3 & 0 \end{pmatrix}^T = \begin{pmatrix} 0 & -1 & 2 \\ -1 & 0 & 3 \\ 2 & 3 & 0 \end{pmatrix}$

Antisymetrická matice

$${}^I \theta_{ij} : (B)_{ij} = -(B)_{ji} \iff \boxed{B = -B^T}$$

Pr. $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 3 \\ +2 & 3 & 0 \end{pmatrix}$

Věta: Každou ekvivalentní lze jednoduše

matrici na součet symetrické a antisym.

$$\begin{aligned}
 \mathbb{B} &= \underbrace{\frac{1}{2}(\mathbb{B} + \mathbb{B}^T)}_{=\mathbb{B}^S} + \underbrace{\frac{1}{2}(\mathbb{B} - \mathbb{B}^T)}_{=\mathbb{B}^A} \\
 &= \mathbb{B}^S : \frac{1}{2}(\mathbb{B} + \mathbb{B}^T)^T = \frac{1}{2}(\mathbb{B} + \mathbb{B}^T) \\
 &= \mathbb{B}^A : \frac{1}{2}(\mathbb{B} - \mathbb{B}^T)^T = -\frac{1}{2}(\mathbb{B} - \mathbb{B}^T) \\
 &\quad \quad \quad ((\mathbb{B}^T)^T = \mathbb{B})
 \end{aligned}$$

Př. Porovnejte $\begin{pmatrix} 1 & 2 & 3 \\ -1 & 2 & 1 \\ 2 & 0 & 0 \end{pmatrix}$ na $\mathbb{B}^S + \mathbb{B}^A$

$$\mathbb{B}^S = \frac{1}{2} \left(\begin{pmatrix} 1 & 2 & 3 \\ -1 & 2 & 1 \\ 2 & 0 & 0 \end{pmatrix} + \begin{pmatrix} 1 & 2 & 3 \\ -1 & 2 & 1 \\ 2 & 0 & 0 \end{pmatrix}^T \right) = \dots$$

$$= \begin{pmatrix} 1 & 1/2 & 5/2 \\ 1/2 & 2 & 1/2 \\ 5/2 & 1/2 & 0 \end{pmatrix}$$

$$\mathbb{B}^A = \mathbb{B} - \mathbb{B}^S = \begin{pmatrix} 1 & 2 & 3 \\ -1 & 2 & 1 \\ 2 & 0 & 0 \end{pmatrix} - \begin{pmatrix} 1 & 1/2 & 5/2 \\ 1/2 & 2 & 1/2 \\ 5/2 & 1/2 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 3/2 & 1/2 \\ -3/2 & 0 & 1/2 \\ -1/2 & -1/2 & 0 \end{pmatrix}$$

Determinanty

$$1. \quad \begin{vmatrix} 1 & & & \\ & 1 & & \\ & & \ddots & \\ & & & 1 \end{vmatrix} = 1$$

$$2. \left| \bar{a}_1^s, \dots, \bar{a}_{i-1}^s, \alpha \bar{u} + \beta \bar{v}, \bar{a}_{i+1}^s, \dots, \bar{a}_n^s \right| \quad (\text{multi-lin.})$$

$$= \alpha \cdot \left| \bar{a}_1^s, \dots, \bar{u}, \dots, \bar{a}_n^s \right| + \beta \cdot \left| \bar{a}_1^s, \dots, \bar{v}, \dots, \bar{a}_n^s \right|$$

$$3. \left| \bar{a}_1^s, \dots, \bar{a}_i^s, \dots, \bar{a}_j^s, \dots, \bar{a}_n^s \right| = - \left| \bar{a}_1^s, \dots, \bar{a}_j^s, \dots, \bar{a}_i^s, \dots, \bar{a}_n^s \right|$$

(antisymmetrie)

4. $\begin{vmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{j1} & \dots & a_{jn} \\ \vdots & \ddots & \vdots \\ a_{i1} & \dots & a_{in} \\ \vdots & \ddots & \vdots \\ a_{n1} & \dots & a_{nn} \end{vmatrix} = - \begin{vmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{i1} & \dots & a_{in} \\ \vdots & \ddots & \vdots \\ a_{j1} & \dots & a_{jn} \\ \vdots & \ddots & \vdots \\ a_{n1} & \dots & a_{nn} \end{vmatrix} = 0$

$c_i = -c_j \Rightarrow c_i = 0$

Gausssche Upreue

$$\begin{vmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{i1} & \dots & a_{in} \\ \vdots & \ddots & \vdots \\ a_{j1} & \dots & a_{jn} \\ \vdots & \ddots & \vdots \\ a_{n1} & \dots & a_{nn} \end{vmatrix} \stackrel{\text{lineare}}{=} a_{11} \begin{vmatrix} a_{12} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{i2} & \dots & a_{in} \\ \vdots & \ddots & \vdots \\ a_{j2} & \dots & a_{jn} \\ \vdots & \ddots & \vdots \\ a_{n2} & \dots & a_{nn} \end{vmatrix} + 0 + \dots + 0 + \alpha_i \begin{vmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{i1} & \dots & a_{in} \\ \vdots & \ddots & \vdots \\ a_{j1} & \dots & a_{jn} \\ \vdots & \ddots & \vdots \\ a_{n1} & \dots & a_{nn} \end{vmatrix} + 0 + \dots$$

$= 0$

$$A \xrightarrow[\alpha_i \neq 0]{\bar{a}_i := \sum_{j=1}^m \alpha_j a_j^i} \tilde{A} : |A| = \alpha_i \cdot |\tilde{A}|$$

Determinant trojúhelníkové matice

$$\begin{vmatrix} u_{11} & \dots & \dots \\ \vdots & \ddots & \vdots \\ 0 & u_{m-1,m-1} & \underbrace{u_{m-1,m}}_{u_{m,m}} \end{vmatrix} \quad \underline{\underline{r_{m-1} := 1 \cdot r_{m-1} - \frac{u_{m-1,m}}{u_{m,m}} \cdot r_m}}$$

$$= \begin{vmatrix} u_{11} & \dots & \dots \\ \vdots & \ddots & \vdots \\ 0 & \vdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & u_{m-1,m-1} & 0 \\ \vdots & \ddots & \vdots \\ 0 & \vdots & u_{m,m} \end{vmatrix} = \dots$$

$$= \begin{vmatrix} u_{11} & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & u_{m,m} \end{vmatrix} \quad \underbrace{= u_{11} u_{22} \dots u_{m,m}}_{=1} \quad \begin{vmatrix} 1 & 0 \\ \vdots & \vdots \\ 0 & 1 \end{vmatrix} = 1$$

Př. $\begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix} \xrightarrow{-3r_1} \begin{vmatrix} 1 & 2 \\ 0 & -2 \end{vmatrix} = 1 \cdot (-2) = -2$

$$r_2 = r_2 - 3r_1$$

1 1 2 1 1 1 1 1 1 1

$$\begin{pmatrix} 1 & -1 & 2 \\ 2 & 0 & -1 \end{pmatrix} \begin{matrix} r_2: \cancel{1}r_2 - 1r_1 \\ r_3: \cancel{1}r_3 - 2r_1 \end{matrix} \xrightarrow{1.1} \begin{pmatrix} 1 & -1 & 2 \\ 0 & 3 & 1 \\ 0 & 2 & -5 \end{pmatrix} \begin{matrix} r_2: \cancel{3}r_2 - 2r_3 \end{matrix}$$

$$= \frac{1}{3} \begin{vmatrix} 1 & \dots & \dots \\ 0 & 3 & \dots \\ 0 & 0 & -17 \end{vmatrix} = \frac{1 \cdot 3 \cdot (-17)}{3} = \underline{\underline{-17}}$$

$$\begin{pmatrix} 1 & -1 & 2 & 1 \\ 2 & 1 & -1 & 0 \\ 2 & 2 & 0 & 1 \\ 1 & -1 & 3 & 2 \end{pmatrix} \begin{matrix} -2r_1 \\ -2r_1 \\ -r_1 \end{matrix} = \begin{pmatrix} 1 & -1 & 2 & 1 \\ 0 & 3 & -5 & -2 \\ 0 & 4 & -4 & -1 \\ 0 & 0 & 1 & 1 \end{pmatrix} \begin{matrix} r_3: \cancel{8}r_3 - 4r_2 \end{matrix}$$

$$= \frac{1}{2} \cdot \begin{vmatrix} 1 & \dots & \dots \\ 0 & 3 & \dots \\ 0 & 8 & 5 \\ 0 & 1 & 1 \end{vmatrix} \begin{matrix} r_4: \cancel{8}r_4 - r_3 \end{matrix}$$

$$= \frac{1}{3} \cdot \frac{1}{8} \begin{vmatrix} 1 & \dots & \dots & \dots \\ \dots & 3 & \dots & \dots \\ \dots & \dots & 8 & \dots \\ \dots & \dots & 0 & 3 \end{vmatrix} = \frac{1}{3 \cdot 8} \cdot 1 \cdot 3 \cdot 8 \cdot 3 = \underline{\underline{3}}$$

quadrant

$$\begin{vmatrix} 0 & 1 \\ 2 & 1 \end{vmatrix} \begin{matrix} \curvearrowright \\ \curvearrowleft \end{matrix} = \begin{vmatrix} 2 & 1 \\ 0 & 1 \end{vmatrix} = -2 \cdot 1 = \underline{\underline{-2}}$$

$$\begin{matrix} // \\ 0 \cdot 1 - 1 \cdot 2 \\ = -2 \end{matrix} \quad \begin{matrix} // \\ 2 \cdot 1 - 1 \cdot 0 \\ // \\ +2 \end{matrix}$$